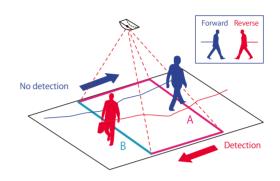
# **\$** ACCURANCE **R1002**

# Reverse detection system



Reverse Detection System R1002 with an unique detection algorithm [Vector Focal Method] is designed to detect backward movement of human(s) in a specific area. The system are suitable for applications to catch a suspicious individual such as airports for an efficient facility management or security.



## FEATURES

### Accurate detection

An unique detection method [Vector Focal Method] grasps and tracks a shape of human sterically.

### Reverse detection

Grasp all human movements and detect only backward movement

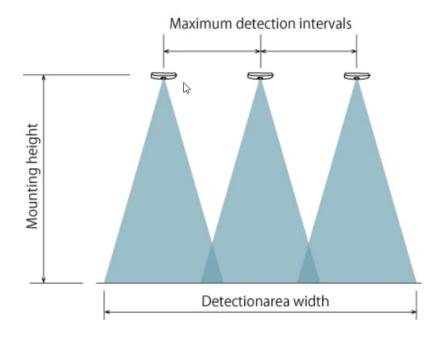
## System corporation

Enable to be connected with an upper layer system by using no-voltage output from the control box.

#### SPECIFICATIONS Specifications Remarks Detection Method Vector Focusing Method Detection Accuracy > 95% (by own criteria) Power over Ethernet IEEE 802.3 af Supply Voltage Warm-up time Approx. 45 sec Control box 10 W max Power Consumption Detection unit 10 W max. Power (lit) Green Reverse detection (lit) Green / Red Warm-up (lit) / Trouble (blinking) Communication trouble (alternative blinking) Indicator Detection unit Green Power (lit) Red Reverse detection (lit) Warm-up (lit) / Trouble (blinking) Orange Communication trouble (alternative blinking) Green / Red Control box $265 \times 135 \times 31 \text{ mm}$ $(W \times H \times D)$ Dimensions 193 × 85 × 34 mm $(W \times H \times D)$ Detection unit Control box 800 g Weight Detection unit 220 g Operating Temperature 0 to 50°0 Operating Humidity only under < 80% RH only under no condensation no condensation Operating Illuminance only the 100 to 20,000 lux \*1 only the outline of an object is shown outline of an object is show Control box Wall / stationary Interior only Install location Detection unit Ceiling Interior only Mounting Height Detection unit It may be limited by environmental conditions. CAT5e or large 100 m max. in length Protocol : TCP/UDP(IPv4), ARP, ICMP or HTTP 100Base-T(X) Ethernet Disable output Disable reverse detection [1] and [2] Input terminal \*2 Output reset Stop the outputs of reverse detection [1] and [2] Reverse detection [1] Variable timer 0.2 to infinity Reverse detection [2] MOS FET relay Unit [1] detects Pulse output for reverse detection by unit [1] Pulse output for the number of reverse detection by unit [1] N.O./N.C. no voltage Output terminal \*2 Unit [2] detects Pulse output for reverse detection by unit [2] Pulse output for the number of reverse detection by unit [2] 30 V DC 0.2 A or less Unit [3] detects Pulse output for reverse detection by unit [3] Pulse output for the number of reverse detection by unit [3] (Resistibility load) Number of reverse detections Pulse output for the number of reverse detection Output when disable to detect

<sup>\*1</sup> R1002 always requires 100 lux or more.
\*2 Input/output relays can be selected N.O./N.C. by the dipswitch

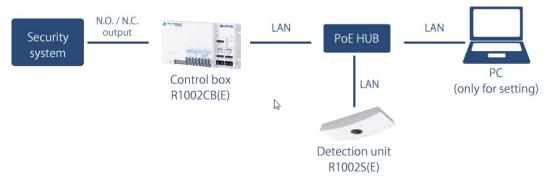
# Optex OPXR1002CB(E) Detection Area:



[Unit:mm]

Mounting height	Detection area width			Maximum installation intervals
	One unit	Two units	Three units	
2500	1500	2700	3900	1200
3000	2700	5100	7500	2400
3500	3300	6300	9300	3000
4000	4000	7700	11400	3700

# System configuration

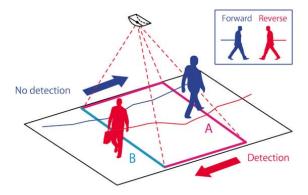


₩Up to 3 units for 1 control box

# Optex OPXR1002CB(E) Scenarios:

# Principle

As the left figure shows, when a passer by crosses two lines of pink (A) and light blue (B) in oppsite directions, a "Reverse" outout will be activated.



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  - An unique detection method [Vector Focal Method] grasps and tracks a shape of human sterically.
- Grasp all human movements and detect only backward movement
- System corporation
   Enable to be connected with an upper layer system by using no-voltage output from the control box.

